Static and Dynamic Analysis of the Internet's Susceptibility to Faults and Attacks

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Abstract-We analyze the susceptibility of the Internet to random faults, malicious attacks, and mixtures of faults and attacks. We analyze actual Internet data, as well as simulated data created with network models. The network models generalize previous research, and allow generation of graphs ranging from uniform to preferential, and from static to dynamic. We introduce new metrics for analyzing the connectivity and performance of networks which improve upon metrics used in earlier research. Previous research has shown that preferential networks like the Internet are more robust to random failures compared to uniform networks. We find that preferential networks, including the Internet, are more robust only when more than 95% of failures are random faults, and robustness is measured with average diameter. The advantage of preferential networks disappears with alternative metrics, and when a small fraction of faults are attacks. We also identify dynamic characteristics of the Internet which can be used to create improved network models. This model should allow more accurate analysis for the future Internet, for example facilitating the design of network protocols with optimal performance in the future, or predicting future attack and fault tolerance. We find that the Internet is becoming more preferential as it evolves. The average diameter has been stable or even decreasing as the number of nodes has been increasing. The Internet is becoming more robust to random failures over time, but has also become more vulnerable to attacks.

I. INTRODUCTION

Many biological and social mechanisms—from Internet communications [1] to human sexual contacts [2]—can be modeled using the mathematics of networks. Depending on the context, policymakers may seek to impair a network (e.g., to control the spread of a computer or bacterial virus) or to protect it (e.g., to minimize the Internet's susceptibility to distributed denial-of-service attacks). Thus a key characteristic to understand in a network is its robustness against failures and intervention. As networks like the Internet grow, random failures and malicious attacks can cause damage on a proportionally larger scale—an attack on the single most connected hub can degrade the performance of the network as a whole, or sever millions of connections. With the ever increasing threat of terrorism threat, attack and fault tolerance becomes an important factor in planning network topologies and strategies for sustainable performance and damage recovery.

A network consists of nodes and links (or edges), which often are damaged and repaired during the lifetime of the network. Damage can be complete or partial, causing nodes and/or links to malfunction, or to be fully destroyed. As a result of damage to components, the network as a whole deteriorates: first, its performance degrades, and then it fails to perform its functions as a whole. Measurements of performance degradation and the threshold of total disintegration depend on the specific role of the network and its components. Using random graph terminology [3], disintegration can be seen as a phase transition from degradation—when degrading performance crosses a threshold beyond which the quality of service becomes unacceptable.

Network models can be divided into two categories according to their generation methods: static and evolving (growing) [4]. In a static network model, the total number of nodes and edges are fixed and known in advance, while in an evolving network model, nodes and links are added over time. Since many real networks such as the Internet are growing networks, we use two general growing models for comparison—growing exponential (random) networks, which we refer to as the GE model, where all nodes have roughly the same probability to gain new links, and growing preferential (scale-free) networks, which we refer to as the Barabási-Albert (BA) model, where nodes with more links are more likely to receive new links. Note that [5] used two general network models, a static random network and a growing preferential network.

For our study, we extend the modeling space to a continuum of network models with *seniority*, adding another dimension in addition to the *uniform* to *preferential* dimension. We extend the simulated failure space to include mixed sequences of failures, where each failure corresponds to either a fault or an attack. In previous research, failure sequences consisted either solely of faults or attacks; we vary the percentage of attacks in a fault/attack mix via a new parameter β which allows us to simulate more typical scenarios where nature is somewhat

malicious, e.g., with $\beta \approx 0.1$ (10% attacks).

We analyze both static and dynamic susceptibility of the Internet to faults and attacks. In static analysis, we first reconfirm previous work of Albert et al. [5]. Based on these results, we address the problems of existing metrics, the average diameter and the S metric, and propose new network connectivity metrics, K and DIK. Second, we put that result to test by diluting the sequence of faults with a few attacks, which quickly strips scale-free networks of any advantage in resilience. Our study shows that scale-free networks including the Internet do not have any advantage at all under a small fraction of attacks $(\beta > 0.05 (5\%))$ with all metrics. Moreover, we show that the Internet is much more vulnerable under a small fraction of attacks than the BA model-even 1% of attacks decrease connectivity dramatically. In dynamic analysis, we trace the changes of the Internet's average diameter and its robustness against failures while it grows. Our study demonstrates that the Internet has been becoming more preferential over time and its susceptibility under attacks has been getting worse. Our results imply that if the current trend continues, the threat of attack will become an increasingly serious problem in the future.

Finally, we analyze 25 Internet topologies examined from November, 1997 to September, 2001, and perform a detailed analysis of dynamic characteristics of the Internet. These results provide insight into the evolution of the Internet, may be used to predict how the Internet will evolve in the future, and may be used to create improved network models.

II. PREVIOUS WORK

Network topology ties together many facets of a network's life and performance. It is studied at the overall topology level [6], link architecture [7], [8], and end-to-end path level [9], [10]. Temporal characteristics of a network are inseparable consequences of its connectivity. This linkage is apparent from [11], [12], [13]. Scaling factors, such as power-law relationships and Zipf distributions, arise in all aspects of network topology [6], [14] and web-site hub performance [15].

Topology considerations inevitably arise in clustering clients around demanding services [16], strategically positioning "digital fountains" [17], and mobile positioning [18] *etc. ad infinitum*. In QoS and *any*cast, topology dictates growing overlay trees, reserved links and nodes, and other sophisticated connectivity infrastructure affecting overall bandwidth through hubs and bottlenecks [19], [20], [21]. Other special connectivity infrastructures include P2P netherworlds [22] and global, synchronizable storage networks with dedicated topology and infrastructure for available, survivable network application platforms such as the Intermemory [23], [24], [25].

An important aspect which shows up more and more is fault control [26]. Several insights have come from physics, with the cornerstone work by Barabási [5], and further detailed network evolution models, including small worlds and Internet breakdown theories [4], [27], [28], [29], [30], [31], [32].

Albert, Jeong, and Barabási [5] examine the dichotomy of *exponential* and *scale-free* networks in terms of their response

to errors. They found that while exponential networks function equally well under random faults and targeted attacks, scalefree networks are more robust to faults but susceptible to attacks. Because of their skeletal hub structure, preferential networks can sustain a lot of faults without much degradation in *average distance*, \overline{d} , a metric also introduced in [5] to aggregate connectivity of a possibly disconnected graph in a single number.

Recent research [33], [34] has argued that the performance of network protocols can be seriously effected by the network topology and that building an effective topology generator is at least as important as protocol simulations. Previously, the Waxman generator [35], which is a variant of the Erdos-Renyi random graph [3], was widely used for protocol simulation. In this generator, the probability of link creation depends on the Euclidean distance between two nodes. However, since real network topologies have a hierarchical rather than random structure, next generation network generators such as Transit-Stub [36] and Tiers [37], which explicitly inject hierarchical structure into the network, were subsequently used. In 1999, Faloutsos *et al.* [6] discovered several power-law distributions about the Internet, leading to the creation of new Internet topology generators.

Tangmunarunkit *et al.* divide network topology generators into two categories [38]: *Structural* and *Degree-Based* network generators. Other recently proposed generators are [1], [14], [39], [40], [41], [42]. The major difference between these two categories is that the former explicitly injects hierarchical structure into the network, while the later generates graphs with power-law degree distributions without any consideration of network hierarchy. Tangmunarunkit *et al.* argue that even though degree-based topology generators do not enforce hierarchical structure in graphs, they present a loose hierarchical structure, which is well matched to real Internet topology.

Characteristics of the Internet topology and its robustness against failures have been widely studied [1], [5], [6], [14], with focus on extracting common regularities from several snapshots of the real Internet topology.¹ On the other hand, [42], [43] have shown that the clustering coefficient of the Internet has been growing and that the average diameter of the Internet has been decreasing over the past few years.² However, [43] used this characteristic only as evidence of topology stability.

III. NETWORK MODEL AND SIMULATION ENVIRONMENT

Network models can be divided into two categories according to their generation methods: static and evolving (growing) [4]. In an evolving model, nodes are added over time—time goes in steps, and at each time step a node and m links are added. The probabilities in such a network are time-dependent (because the total number of nodes/edges changes with each time-step). In a static network model, the total number of nodes and edges are fixed and known in advance. Note that this

¹Those characteristics, e.g., power-law of the degree distribution, we define as *Static Characteristics* because of their consistency over time.

²We define these as *Dynamic Characteristics* of the Internet.

difference between the models affects the probability of each node to gain new edges—old nodes have a higher probability than new nodes to gain new edges in an evolving network model. Both classes of models can be placed at the edges of a *seniority* continuum, defined as follows. Seniority is a probability σ that all of the *m* edges of this iteration will be added immediately, or at the end of time. A seniority value of 1 corresponds to a pure time-step model, and a seniority value of 0 represents a pure static model.

In our simulations, we use a modified version of the model in [44] for comparison with the Internet. The model contains a parameter, α , which quantifies the natural intuition that every vertex has at least some baseline probability of gaining an edge. In [44], both endpoints of edges are chosen according to a mixture of probability α for preferential attachment and $1 - \alpha$ for uniform attachment. Let k_i be the degree of the *i*th node and *m* denotes the number of edges introduced at each time-step. If m_0 represents the number of initial nodes and *t* denotes the number of time-steps, the probability that an endpoint of a new edge connects to vertex *i* is

$$\Pi(k_i) = \alpha \frac{k_i}{2mt} + (1-\alpha) \frac{1}{m_0 + t}.$$

An α value of 0 corresponds to a fully uniform model, while α values close to 1 represent mostly preferential models.

When an evolving network is generated, we initially introduce a seed network with two nodes and an edge between them $(n_0 = 2, e_0 = 1)$ ³ Then, at each time-step, after a new node is introduced, new edges can be located with two different edge increment methods: external-edge-increment [5], [1] and internal-edge-increment [44]. In a growing exponential network with the external-edge-increment method, a new node is connected to a randomly chosen existing node. However, with internal-edge-increment, new edges are added between two arbitrary nodes chosen randomly. In our experiment, unlike [44], we apply external-edge-increment instead of internaledge-increment because preferential networks generated by internal-edge-increment contain too many isolated nodes. Note that when α equals 1, preferential networks in our experiments are the same as the Barabási-Albert (BA) model in [1], [5], which is very similar to the network in [44] with $\alpha = 0.5$.

Failures can be characterized as either *faults* or *attacks* [5]. Faults are random failures, which affect a node independent of its network characteristics, and independent of one another. On the other hand, attacks maliciously target specific nodes, possibly according to their features (e.g., connectivity, articulation points, etc.), and perhaps forming a strategic sequence. The topology of the network affects how gracefully its performance degrades, and how late disintegration occurs. To measure robustness of networks against mixed failures, we use β for characterizing failures. With probability 1 - β , a failure is a random fault destroying one node chosen uniformly. Otherwise (probability β), the failure is an attack that targets the single

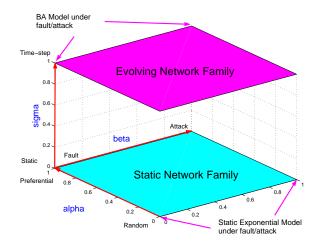


Fig. 1. Phase space of the network models in our study. We conducted experiments with both the evolving network family (pure time-step models) and the static network family. We focus on the evolving network family because most real networks are considered to be evolving networks.

most connected node. When β equals 1, all failures are attacks, and when β equal 0, all failures are faults.

Figure 1 shows the phase space of different network models. We conducted experiments with both the evolving network family (pure time-step models) and the static network family. However, in this paper we mainly compare the robustness of two different types of evolving networks: evolving exponential (uniform) networks and evolving scale-free (preferential) networks, because many real networks, such as the Internet and the World Wide Web, are considered to be evolving networks.

We implemented our simulation environment in C++ with LEDA [45]⁴. The networks are derived from LEDA's *graph* type, with additional features and experiments as separate modules. We do not allow duplicate edges and self-loops in our models and we delete all self-loop links from the Internet.

Like [5], the Internet's robustness against failures can be measured from a snapshot of the Internet. We call this kind of analysis *Static Analysis*. However, the Internet is a growing network and its topology changes continuously. Does the growth mechanism of the Internet affect its robustness? How is the Internet's robustness changing while it is growing? Will performance and robustness of the Internet improve in the future? To answer these questions, we analyze historical Internet topologies. We call this *Dynamic Analysis*. In this paper, we mainly compare the robustness of the Internet with two different network models, the BA model and a growing exponential network model (GE model).

IV. STATIC ANALYSIS OF THE INTERNET'S SUSCEPTIBILITY TO FAULTS AND ATTACKS

A. Metrics

As noted in [46], finding a good connectivity metric remains an open research question. [5] introduced two important metrics, \overline{d} and S. The average diameter or average shortest path

 $^{{}^{3}}A$ seed network is needed to generate a network using the preferential model—the probabilities of new links for all initial nodes at t = 1 are zero if there are no initial links.

⁴Library of Efficient Data types and Algorithms (LEDA), available at http://www.algorithmic-solutions.com/.

length, \overline{d} , is defined as follows: let d(v, w) be the length of the shortest path between nodes v and w; as usual, $d(v, w) = \infty$ if there is no path between v and w. Let Π denote the number of distinct node pairs (v, w) such that $d(v, w) \neq \infty$ where $v \neq w$.

$$\overline{d} = \frac{\sum_{(v,w)\in\Pi} d(v,w)}{|\Pi|}$$

where $v \neq w$. To evaluate the reliability of the \overline{d} metric, we started with measuring the robustness of three different evolving networks under faults or attacks only. Our experiments are somewhat different from [5]. We compared behaviors of the growing scale-free network (the BA model) and the Internet with those of the growing random network (the GE model), while [5] used static exponential networks for comparison.

As we expected, our results are very similar to [5]; A growing exponential network performs worse under faults, but better under attacks. However, as we can see in Figure 2(a), d is not always representative of the overall connectivity because it ignores the effect of isolated nodes in the network. Note that \overline{d} is decreasing rapidly after a certain threshold under attacks only, showing that when the graph becomes sparse, \overline{d} is less meaningful. The other metric, S, is defined as the ratio of the number of nodes in the giant connected component divided by the total number of nodes. One might notice the different characteristics of the two metrics. Shorter average diameter means shorter latency. It demonstrates how fast a network can react when an event occurs, providing an indication of the performance of a network. On the other hand, S mainly considers the networks' connectivity, showing how many nodes are connected to the largest cluster.

Since the *S* metric only considers the relative size of the largest connected component, and does not characterize the entire network, we created a new metric, *K*, that describes the whole network connectivity. *K* is defined as follows: let Ψ be the number of distinct node pairs, and Π is defined as above. Then

$$K = \frac{|\Pi|}{|\Psi|}$$

K measures all connected node-pairs in a network. In Figure 2, we can see that the Internet shows the best robustness under faults according to the diameter. However, if we use the K or S metrics, the Internet is most vulnerable even under faults.

One weakness of the *K* metric is that it does not consider the effect of redundant edges. The *K* value for a connected graph with *n* nodes and *n*-1 edges⁵ (*K* = 1, $\overline{d} \ge 1$) is the same as that of a fully connected graph⁶ (*K* = 1, $\overline{d} = 1$) even though the diameter and connectivity of each graph is quite different. To solve this problem, we introduce a modified diameter metric, which we call *Diameter-Inverse-K* (*DIK*). *DIK* is defined as:

$$DIK = \frac{\overline{d}}{\overline{K}}$$

The *DIK* metric uses the *K* metric as a penalty parameter for sparse graphs and measures both the expected distance between two nodes and the probability of a path existing between two arbitrary nodes. Figure 2 demonstrates that dsignificantly decreases when it reaches a certain threshold, while *DIK* continuously increases. Note that the Internet is most vulnerable even under faults if we measure network connectivities with *S* or *K*.

B. Robustness against Mixed Failures

In real life, it is somewhat unrealistic to expect that failures are either all faults or all attacks. One may expect that failures are a mixture of attacks and faults, e.g., only a small fraction of failures are attacks while most failures denote faults. In the following experiments, network destruction was performed until 10% of the total number of nodes was destroyed, using different values of β (probability of attack). We performed 10 runs in each case with different seed numbers. The results in Figure 3 are the average of the ten runs. We define the average diameter ratio as $\overline{d_f}/\overline{d_o}$ where $\overline{d_o}$ denotes the average diameter of the initial network, and $\overline{d_f}$ is the average diameter after 10% of the nodes have failed. Similarly, the DIK ratio is defined as DIK_f/DIK_o where DIK_o is the DIK value of the original network, and DIK_f is the DIK value after 10% of the nodes have failed. Figure 3 shows that: (a) Although there seems to be an advantage for scale-free networks under pure faults, their disadvantage under attacks is much larger, and even a small fraction of attacks, $\beta > 0.05$ (5%), in a mix of failures removes any overall advantage of the scale-free networks. (b) The K metric is even more unforgiving to the scale-free networks, showing no advantage under any $\beta \ge 0.01$ (1%). Note that the Internet shows the worst robustness even under faults only. Figure 3(c) clearly shows the vulnerability of the Internet under a small fraction of attacks. DIK is increasing very rapidly and even 1% of attacks significantly hurts its robustness.

We also measured the effect of preferential attachment and observed the following trends. First, more preferential networks have shorter average diameters. We generated networks with various α and observed this trend, as shown in Figure 4. The most preferential network with n nodes and n-1edges has all nodes connected to the most popular node. The diameter from the most popular node to others is one and the diameter between any two nodes except the most popular node is two, therefore the average diameter is less than two, and the network has the smallest diameter of all possible networks with n nodes and n-1 edges. Second, more preferential networks are more robust under faults only, but more vulnerable under even a small fraction of attacks if we measure robustness using the average diameter or DIK. Figure 5 demonstrates that when α is close to 1, even a small fraction of attacks ($\beta > 0.01$ (1%)) cancels out the advantage of the scale-free networks and hurts their topologies more. Note that if the average diameter reaches a certain threshold, it decrease rapidly and becomes meaningless. Third, with the K metric, a preferential network does not show any

⁵A graph where all nodes are connected to the giant connected component. ⁶A graph where all nodes are connected to all other nodes.

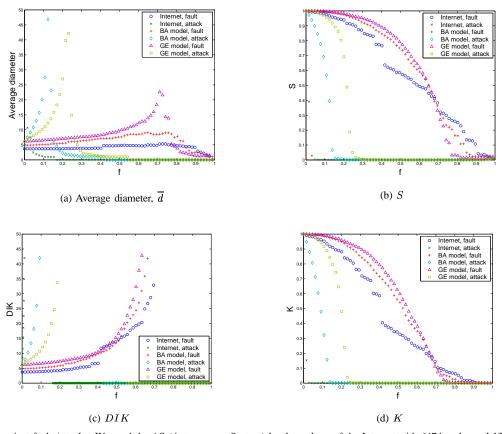


Fig. 2. Robustness against faults/attacks; We used the AS (Autonomous System) level topology of the Internet with 6474 nodes and 13895 edges from [47], which was examined on Jan. 2, 2000. After removing self-loops, the number of edges decreased to 12572. For growing network models, we set *m* equal to two and generated networks with 6474 nodes. *f* denotes the number of failure nodes divided by the total number of nodes in the original network. Two nodes and an edge between them are initially introduced when we generate the network ($n_0 = 2$, $e_0 = 1$). (a) and (c): (a) shows \overline{d} for the Internet, and for the BA and GE models. Note that \overline{d} significantly decreases when it reaches a certain threshold, while *DIK* continuously increases. (b) and (d): The *S* and *K* metrics do not agree with the previous observations using \overline{d} . The Internet is most vulnerable under both attacks and faults using these metrics. Even though *S* and *K* behave very similarly, *S* only considers the relative size of the giant connected component, while *K* considers all node pairs which are connected. We set *DIK* to zero when \overline{d} and *K* becomes zero. Note that smaller is better for \overline{d} and *DIK*, but larger is better for *S* and *K*.

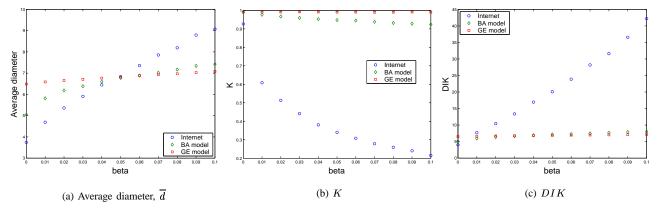


Fig. 3. Robustness of the Internet, and the BA and GE models under mixed failures after 10% of total nodes are destroyed. (a): The average diameter of the Internet and the BA model increases rapidly compared with the GE model as β is increasing. The advantage of smaller \overline{d} disappears when $\beta > 0.05$ (5%). Figure (c) demonstrates this trend more clearly. Note that even 1% of attacks significantly hurts robustness of the Internet. (b): The K metric is even more unforgiving to the scale-free networks, and shows no advantage under any $\beta \ge 0.01$ (1%). The Internet shows the worst robustness even under faults only. The results shown are the average of ten runs. Note that smaller is better for \overline{d} and *DIK*, but larger is better for K.

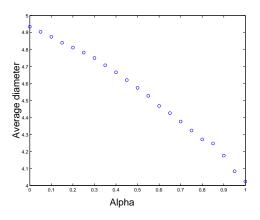


Fig. 4. Relationship between preferentiality and average diameter; While α is increasing, the average diameter of the networks generated is decreasing. Results are the average of 10 different networks with different seed numbers.

noticeable advantage even under attack, and an exponential network dominates all kinds of failures.

V. DYNAMIC ANALYSIS OF THE INTERNET'S SUSCEPTIBILITY TO FAULTS AND ATTACKS

In this section, we measure changes in the Internet's robustness against failures over time. We sampled eight Internet topologies from different points in time from [47]. Selfloop links were removed. First, we measured the average diameter. We also generated the BA model and the GE model and measured their average diameters. While the number of nodes in the Internet increased, the average diameter actually decreased, which can not be explained by the BA model. Both the BA and GE models predict an increasing average diameter as the number of nodes increases, as shown in Figure 6.

Next, we trace the robustness of the Internet while it is growing. For each Internet topology, we destroy 10% of the total number of nodes and measure robustness with three different metrics—average diameter, K, and DIK. Figure 7(a) and 7(d) show the robustness of the Internet with the average diameter. The average diameter ratio of the Internet is decreasing while the number of nodes is increasing under pure faults. Note that the average diameter ratios of other network models are fluctuating and do not show any clear trend. Figure 7(d) is misleading because the Internet topology becomes too sparse after 10% of the nodes are removed. Note that the average diameter is meaningless when a graph contains many isolated nodes. With the K and DIK metrics, we observe a clear trend: the Internet becomes more robust under faults, but more vulnerable under attacks while it grows. In other words, the Internet has been becoming more preferential over time and the growth mechanism of the Internet focuses on maximizing overall performance (decreasing average diameter) rather than robustness against attacks, and the Internet's susceptibility under attacks will be a more serious problem in the future if this trend continues.

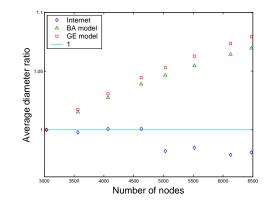


Fig. 6. Diameter ratio while a network is growing. We sampled eight topologies of the Internet, examined on 11/15/1997 (3037 nodes), 04/08/1998 (3564 nodes), 09/08/1998 (4069 nodes), 02/08/1999 (4626 nodes), 05/08/1999 (5031 nodes), 08/08/1999 (5519 nodes), 11/08/1999 (6127 nodes), and 01/02/2000 (6474 nodes), and measured their diameters. For comparison, we also generated the BA and GE models and measured their average diameters. We generated each network model ten times with different seed numbers and calculated average values. Each d_i is divided by d_o , the diameter of the first network with 3037 nodes. d_o is 3.78 for the Internet, 4.51 for the BA model, and 5.20 for the GE model. Note that as the networks are growing, the diameter of the BA and GE models increases, while the diameter of the Internet decreases, indicating a growth mechanism that maximizes performance (minimizing diameter and latency).

VI. DYNAMIC CHARACTERISTICS OF THE INTERNET

Existing Internet topology generators are basically limited since the Internet is a dynamically growing network and its topology and characteristics will have similar dynamics. For example, the clustering coefficient of the Internet has been recently increasing while the average diameter of the Internet has been decreasing [42], [43]. We define these as Dynamic Characteristics of the Internet. Since current Internet topology generators are designed using only the static characteristics of the Internet, we contend that they will suffer from a lack of ability to predict future Internet topology. Currently, the best method to simulate network protocols is using the real Internet topology instead of using Internet topology generators, which innately limits our ability to develop, for example, network protocols that best fit future conditions. We find that most existing Internet topology generators fail to explain some of the dynamic characteristics of the Internet. For example, we found that the average degree of the Internet is frequently changing. It grew until the end of 1999 then decreased until September 2001. Most Internet topology generators do not show this behavior.

Even though degree-based generators represent Internet topologies better than structural ones [38], we contend that current degree-based topology generators only mimic some general properties, i.e. power-law degree distribution, but do not really explain the Internet's growing mechanism [48].

Figure 8 clearly shows this argument. Even though the BA model and the Internet share some general properties such as the degree-frequency distribution, their topology can be very different. Figure 8(a) shows during 1998 the that fraction of nodes with degree one in the Internet is decreasing while

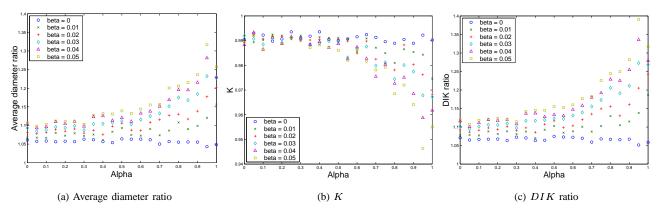


Fig. 5. Robustness of the various network models ($0 \le \alpha \le 1$) under mixed failures after 10% of total nodes are destroyed. Note that larger α means more preferential networks and smaller \overline{d} and *DIK*, but larger *K* means greater robustness. Each network contains 1000 nodes. (a) and (c): \overline{d} ratio and *DIK* ratio increments are growing when β is increasing. However, a small fraction of attacks ($\beta \ge 0.01$ (1%)) cancels out this advantage of the scale-free network and damages preferential networks more. (b): With the *K* metric, preferential networks do not show any noticeable advantage even under attack. The results shown are the average of ten runs.

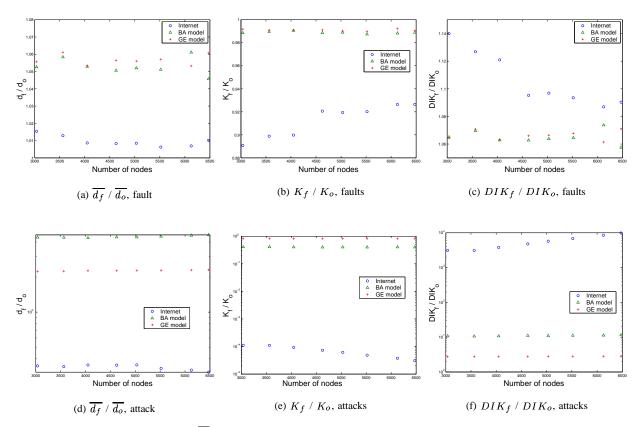


Fig. 7. Dynamic characteristics of the Internet; $\overline{d_o}$, K_o and DIK_o are defined as the average diameter, K, and DIK of the original networks and $\overline{d_f}$, K_f and DIK_f denote the diameter, K, and DIK after 10% of the nodes are removed. Results are the average of ten runs. (a) and (d): (a) shows that the average diameter ratio of the Internet is decreasing while the number of nodes are increasing under pure faults. (d) is misleading because the Internet topology becomes too sparse after 10% of nodes are removed. (b) and (e): While the Internet is growing, the K ratio of the Internet is increasing under faults but decreasing under attacks. (c) and (f): (f) also agrees with previous observations that the Internet becomes more robust under faults but more vulnerable under attacks while it is growing. Note that smaller is better for \overline{d} and DIK, but larger is better for S and K.

that of nodes with degree two is increasing. However, the fraction of nodes with degree k becomes stable after 1999. Note that more than 70% of nodes have degree one or two for the Internet. Figure 8(b) and 8(c) clearly show the limitations of the BA model-like topology generators. First, there are no nodes with degree one. Also, the percentage of nodes with degree more than two in the BA model are twice that for the same nodes in the Internet. Only less than 5% of nodes in the Internet have degree more than four while approximately 10% of nodes in the BA model have degree more than four.

In order to analyze the dynamic characteristics of the Internet topology in detail, we sampled 41 Internet topologies from **Oregon RouteViews**⁷. We first analyze the number of total nodes, node births, and node deaths in the Internet topologies. Since we cannot guarantee that our data set covers entire complete Internet topologies, and that a node may not be discovered because of a temporary failure; we consider a node dead only when it does not appear in future Internet topologies. For example, a node in November, 1997 is considered to be deleted only when it never appears from December, 1997 to September, 2001.

Figure 9(a) shows the regularity in the number of total nodes, added nodes, and deleted nodes over the period of November, 1997 to September, 2001. We also measured the number of total links, added links, and deleted links as shown in Figure 9(b). The total number of nodes and edges increases quadratically and we can predict the number of nodes in the near future with the equations given in Figure 9(a) and 9(b). Average degrees of the Internet topologies are shown in Figure 9(c). In most of the time-step based Internet topology generators including [1], [41], [42], the number of links added at each time-step is fixed. However, the average degree of the Internet increased linearly until the end of 1999 but suddenly decreased from early 2000 even though the number of nodes was increasing. This implies that the approaches of timestep and fixed number of link additions may not generate proper Internet topologies. Calculating the average degree of the Internet analytically with equation (3) showed results very compatible with the changes of the Internet's average degree.

$$N_{nodes} = 3 * X^2 + 58 * X + 3100 \tag{1}$$

$$N_{links} = 4.4 * X^2 + 170 * X + 5300$$
 (2)

$$\overline{k} = \frac{2 * N_{links}}{N_{nodes}} \tag{3}$$

Links can be created by two processes. When a new node is created, new links are created which connect the new node to existing nodes. We previously defined this process as *external edge increment*. Otherwise, links can be added between two existing nodes, defined as *internal edge increment* earlier. In a few cases, we found that a link is created between two new nodes; however, these cases are ignored. Figure 10(a)

shows that 1.36 links per new node are added by external edge increment and 1.86 links per new node are added by internal edge increment over four years starting November 1997. A total of 3.22 links per new node are added over the same time period. Note that internal edge increment affects link increment more than external edge increment. Also, 67% of new nodes are introduced with a single link and 31% of new nodes are added with two links. Only 2% of new nodes are introduced with more than two links over four years; a result shown in 10(b).

Like link births, a link can be deleted in two ways. When a node is dead, links connected to the node are broken. Also, a link can be deleted when any one of the connected nodes decides to be disconnected from the other. We define the former as external edge death and the latter as internal edge death. Node death is not the main factor in link death-link death frequently happens without node death. Around 82% of dead links are broken due to internal edge death. According to Figure 10(d), 1.44 links were broken when a node was discarded. The average number of internal edge deaths is more than three times larger than that of external edge deaths in the same time period. 7.77 links per node death are deleted from November, 1997 to September, 2001. Are less degree nodes more likely to die? One of the interesting observations for link and node death is that more than 74% of dead nodes had degree one, but less than 20% of dead nodes had degree two. Note that there are almost the same number of nodes with degree one and two in the Internet according to Figure 8. Figure 10(e) clearly shows that nodes with fewer connections (i.e. less popular) are more likely to die.

Figure 9(c) and 9(f) show the degree-frequency distribution of new and dead nodes during four years. F(k) can be defined as follows;

$$F(k) = \frac{\sum_{i=1}^{k} f(i)}{N}$$

where f(k) is defined as the number of new (or dead) nodes with degree k. Our results demonstrate that the degreefrequency distribution for new nodes clearly follows a strict power law but deviates significantly for dead nodes.

VII. FUTURE WORK

Our study may be extended in various ways, for example:

• Internet topology generator

Currently, we are designing a new Internet topology generator which fits not only the static characteristics but also the observed dynamic characteristics of the Internet. This generator can be used for simulation to develop network protocols aiming to have optimal performance in the future.

Metrics

New overall connectivity or QoS metrics can be created, for example one possibility is k-disjoint paths: how many paths are there, on average, between any two nodes, which have at least k different edges? Novel

⁷These data were crawled from the web site of **Oregon RouteViews** [47] and **Topology Project Group** [49] in the University of Michigan. They were examined on the 15th of each month from November, 1997 to September, 2001. Since most Internet topology generators and previous work does not consider self-loop links, we removed all self-links.

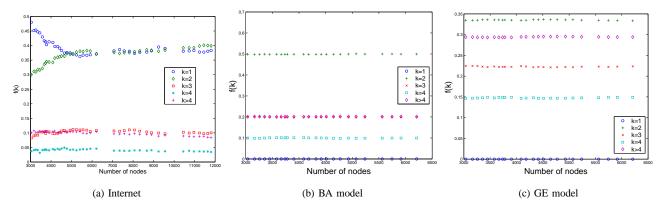


Fig. 8. **Relative size of nodes with degree** k; (a): f(k), the percentage of nodes with degree k. For the Internet, the percentage of nodes with degree one decreases while that of nodes with degree two increases. Note that more than 70% of nodes have degree one or two. (b) and (c): These plots clearly show limitations of the BA model-like topology generators; First, there are no nodes with degree one. Second, the relative fraction of the same degree nodes does not change in our models—changes in Internet topology over time can not be explained by our network model.

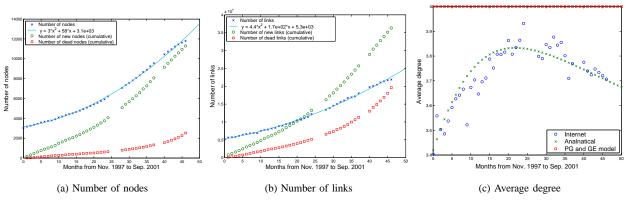


Fig. 9. Dynamic characteristics of the Internet—number of nodes and links, and average degree of the Internet. (a) and (b): The number of nodes/links is increasing quadratically. (c): In most time-step based Internet topology generators including [1], [41], [42], the number of links added at each time-step is fixed. However, the average degree of the Internet increased until Nov. 1999, but decreased linearly while the number of nodes is increasing, a behavior that matches our analytical results.

approaches are also desirable, soliciting actual survivability/performance degradation metrics from other network practitioners.

• Overall performance degradation caused by local network congestion

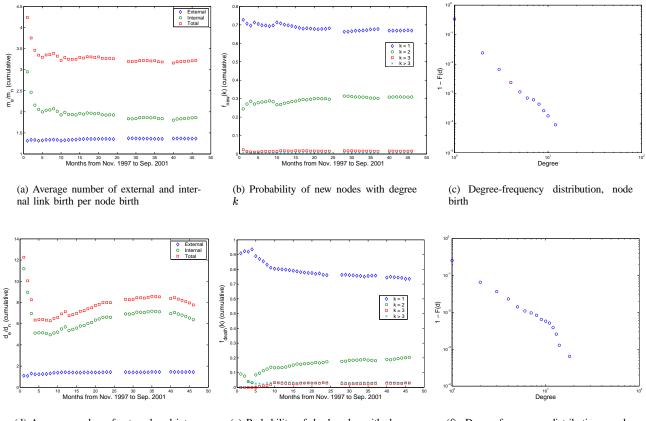
Instead of attacking the most popular nodes, selected edges can be blocked. If user requests in the network increase, the number of requests in the most popular links will increase and may be blocked by network congestion. How will the network as a whole be affected by local network congestion?

VIII. CONCLUSIONS

In our study, we first re-evaluated two basic connectivity metrics, average diameter and S. The average diameter may be a good metric for measuring the performance of networks, but is not always representative of the overall network connectivity. The S metric only considers the relative size of the largest component and ignores other components. To analyze the Internet's susceptibility to faults and attacks, we introduced two new metrics, K and DIK. Unlike S, Kmeasures all connected node-pairs in a network. Also, unlike

average diameter, DIK is still valuable in sparse graphs, and incorporates both the average expected distance between two nodes, and the probability of a path existing between two arbitrary nodes. We also examined the robustness of the Internet under mixed failures. We found that any advantage of scale-free networks, including the Internet, disappeared when a small fraction of failures are attacks, or when using metrics other than the average diameter. We also conducted dynamic analysis of the Internet's susceptibility to attacks and faults, and discovered two interesting results; First, the Internet is much more preferential than the BA model, and its susceptibility under attacks is much larger than even general scale-free networks such as the BA model. Second, the growth mechanism of the Internet stresses maximizing performance, and the Internet is evolving to an increasingly preferential network. If this trend continues, attacks on a few important nodes will be a more serious threat in the future. Finally, we addressed dynamic characteristics of the Internet in detail, finding that:

• The number of nodes and links has been increasing quadratically over time.



(d) Average number of external and internal link birth per node birth

(e) Probability of dead nodes with degree k

(f) Degree-frequency distribution, node death

Fig. 10. Dynamic characteristics of the Internet—average degree, creation of nodes and links, and death of nodes and links; (a): m_n and m_e denotes the number of nodes and links added since November, 1997. In general, 1.36 links per new node are added by external edge increment, and 1.86 links per new node are added by internal edge increment. A total of 3.22 links per new node are added over time. Note that internal edge increment affects link increment more than external edge increment. (b): For external edge increment, 67% of new nodes are created with a single link and 31% of new nodes are added with two links. Only 2% of new nodes are created with more than two links over four year. (d): External edge death is not the main factor in link death. Only about 18% of dead links was due to node deletion and 82% of link deaths occurred without node death. d_n and d_e denote the number of nodes and links deleted since November, 1997. The number of internal edge deaths per node death is more than three times larger than that of external edge death in the same time period. 7.77 links per node death are deleted from November, 1997 to September, 2001. (e): More than 74% of dead nodes have degree one even though the Internet has almost the same number of nodes with degree one and two. This figure shows that less well connected (less popular) nodes are more likely to die. (c) and (f): Degree-frequency distribution for new nodes clearly follows the strict power law but deviates significantly for dead nodes.

- The average degree of the Internet has been changing frequently.
- 67% of new nodes are introduced with single links and 31% of new nodes are introduced with two links. Only 2% of new nodes are introduced with more than two links over four years.
- Two edge increment mechanisms—external edge increment and internal edge increment—affect link birth. In general, 1.36 links per new node are added by external edge increment, and 1.86 links per new node are added by internal edge increment. A total of 3.22 links per new node are added over time.
- Node death is not the main factor in link death. Link death frequently happens without node death. Only about 18% of dead links are due to node death, while 82% occur without node death.
- Less popular nodes are more likely to die. More than 74% of dead nodes have degree one, but less than 20% of

dead nodes have degree two. Note that there are almost the same number of degree-one nodes and degree-two nodes. Only 6% of dead nodes have degree more than two.

• Degree-frequency distribution for new nodes clearly follows a strict power law but deviates significantly from a power law for dead nodes.

The observed characteristics of the Internet topology strongly imply that most of existing network generators, based on only *Static* characteristics of the Internet, may not generate true Internet-like topologies. Moreover, they are limited in their ability to predict future Internet topologies. A direction for future work is the design of Internet topology generators, that generate more realistic Internet-like topologies and give better predictions of the dynamics of future Internet environments.

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